

ON THE MULTIDIMENSIONAL HAAR TRANSFORM

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ABSTRACT. This short technical note summarizes how to compute the multi-dimensional Haar transform both in normal and separable way.

1. 1D FILTERS

The Haar functions are the simplest possible wavelets. The 1D mother wavelet function $\psi(t)$ can be described as:

$$(1) \quad \psi_1(t) = \begin{cases} 1, & \text{for } 0 \leq t < \frac{1}{2} \\ -1, & \text{for } \frac{1}{2} \leq t < 1 \\ 0, & \text{otherwise.} \end{cases}$$

The corresponding scaling function $\phi(t)$ is described as:

$$(2) \quad \phi_1(t) = \begin{cases} 1, & \text{for } 0 \leq t < 1 \\ 0, & \text{otherwise.} \end{cases}$$

2. 2D FILTERS AND 3D FILTERS

2D Haar functions can be constructed using tensor products as follows:

$$(3) \quad 2D = \begin{cases} \psi_2^1 = \psi_1 \otimes \phi_1 \\ \psi_2^2 = \phi_1 \otimes \psi_1 \\ \psi_2^3 = \psi_1 \otimes \psi_1 \\ \phi_2 = \phi_1 \otimes \phi_1. \end{cases}$$

In the same way, 3D filters are:

$$(4) \quad 3D = \begin{cases} \psi_3^1 = \psi_2^1 \otimes \psi_1 \\ \psi_3^2 = \phi_2^2 \otimes \psi_1 \\ \psi_3^3 = \psi_2^3 \otimes \psi_1 \\ \psi_3^4 = \psi_2^4 \otimes \psi_1 \\ \psi_3^5 = \psi_2^1 \otimes \phi_1 \\ \psi_3^6 = \phi_2^2 \otimes \phi_1 \\ \psi_3^7 = \psi_2^3 \otimes \phi_1 \\ \phi_3 = \phi_2 \otimes \phi_1. \end{cases}$$

3. HIGHER DIMENSIONS

The number of functions needed depends of the number of dimensions as 2^d , where d are the dimensions. So there are two filters for 1D (2^1), four filters for 2D (2^2), eight filters for 3D (2^3) and so on.

For the 4D case the filters are:

$$(5) \quad 4D = \begin{cases} \psi_4^1 = \psi_3^1 \otimes \psi_1 \\ \dots \\ \psi_4^{15} = \psi_3^7 \otimes \phi_1 \\ \phi_4 = \phi_3 \otimes \phi_1. \end{cases}$$

Hence, generalizing to any dimensions:

$$(6) \quad nD = \begin{cases} \psi_n^1 = \psi_{n-1}^1 \otimes \psi_1 \\ \dots \\ \psi_n^{2^n-1} = \psi_{n-1}^k \otimes \phi_1 \\ \phi_n = \phi_{n-1} \otimes \phi_1. \end{cases}$$

4. HAAR TRANSFORM

The Haar transform is the simplest of the wavelet transforms. This transform is computed by convolving the signal to be transformed with all necessary Haar functions and by subsampling accordingly afterwards.

The single-level 1D transform \hat{x} is described by the following two 1D-convolutions:

$$(7) \quad \hat{x}(k_1) = \begin{cases} \sum_{u_1=-\infty}^{\infty} \psi_1(u_1)x(k_1 - u_1) \\ \sum_{u_1=-\infty}^{\infty} \phi_1(u_1)x(k_1 - u_1) \end{cases}$$

and by analogy the 2D transform is given by the following four 2D-convolutions:

$$(8) \quad \hat{x}(k_1, k_2) = \begin{cases} \sum_{u_1=-\infty}^{\infty} \sum_{u_2=-\infty}^{\infty} \psi_2^1(u_1, u_2)x(k_1 - u_1, k_2 - u_2) \\ \sum_{u_1=-\infty}^{\infty} \sum_{u_2=-\infty}^{\infty} \psi_2^2(u_1, u_2)x(k_1 - u_1, k_2 - u_2) \\ \sum_{u_1=-\infty}^{\infty} \sum_{u_2=-\infty}^{\infty} \psi_2^3(u_1, u_2)x(k_1 - u_1, k_2 - u_2) \\ \sum_{u_1=-\infty}^{\infty} \sum_{u_2=-\infty}^{\infty} \phi_2(u_1, u_2)x(k_1 - u_1, k_2 - u_2). \end{cases}$$

In previous equations the interval of u variables is infinite; in practice however, convolutions are usually computed for finite intervals. Generalizing to d dimensions, then we will have \hat{x} computed by 2^d d -dimensional convolutions:

$$(9) \quad \hat{x}(k_1, \dots, k_d) = \begin{cases} \sum_{u_1=-\infty}^{\infty} \dots \sum_{u_d=-\infty}^{\infty} \psi_d^1(u_1, \dots, u_d)x(k_1 - u_1, \dots, k_d - u_d) \\ \dots \\ \sum_{u_1=-\infty}^{\infty} \dots \sum_{u_d=-\infty}^{\infty} \psi_d^{2^d-1}(u_1, \dots, u_d)x(k_1 - u_1, \dots, k_d - u_d) \\ \sum_{u_1=-\infty}^{\infty} \dots \sum_{u_d=-\infty}^{\infty} \phi_d(u_1, \dots, u_d)x(k_1 - u_1, \dots, k_d - u_d). \end{cases}$$

4.1. Separable convolutions. Computing multidimensional convolutions can be complicated or too impractical sometimes. For this reason, in some specific cases, a multidimensional convolution can be computed as one-dimensional convolution along all dimensions. The necessary condition to have convolution computed this way is that at least one of the signals being convolved must be *separable*. A signal is said to be separable if it can be written as product of one-dimensional signals:

$$(10) \quad x(u_1, \dots, u_d) = f_1(u_1)f_2(u_2)\dots f_d(u_d) = \prod_{d=1}^D f_d(u_d).$$

In this case we can compute the so-called *row-column* convolution, described below.

4.1.1. *2D case.* Given a 2D-signals x and the 2D Haar functions as described above, than a separable convolution for the 2D Haar transform is described as:

$$(11) \quad \hat{x}(k_1, k_2) = \sum_{u_1=-\infty}^{\infty} \sum_{u_2=-\infty}^{\infty} \psi_2^p(u_1, u_2)x(k_1 - u_1, k_2 - u_2)$$

$$(12) \quad = \sum_{u_1=-\infty}^{\infty} \sum_{u_2=-\infty}^{\infty} \psi_2^{(p,1)}(u_1)\psi_2^{(p,2)}(u_2)x(k_1 - u_1, k_2 - u_2)$$

$$(13) \quad = \sum_{u_1=-\infty}^{\infty} \psi_2^{(p,1)}(u_1) \left[\sum_{u_2=-\infty}^{\infty} \psi_2^{(p,2)}(u_2)x(k_1 - u_1, k_2 - u_2) \right]$$

for any filter p of the 2D Haar functions.

4.1.2. *General n -dimensional case.* The multidimensional Haar transform can be computed as sequences of 1D Haar transform along all dimensions. A separable convolution for the d -dimensional Haar transform can be written infact as:

$$(14) \quad \sum_{u_1=-\infty}^{\infty} \psi_d^{(p,1)}(u_1) \left[\sum_{u_2=-\infty}^{\infty} \psi_d^{(p,2)}(u_2) \dots \left[\sum_{u_d=-\infty}^{\infty} \psi_d^{(p,d)}(u_d)x(k_1 - u_1, \dots, k_d - u_d) \right] \dots \right].$$